## Line Tracker Instruction: Interactive Version

Rev. C, February 21, 2013



### Access Laser Company

where innovation never stops

## Main Features

- Robust stabilization allows field applications where ambient environment changes.
- Stabilization without the side-effect of "chirping" inherent with the traditional dithering scheme.
- Power, spectrum, longitudinal mode and transverse modes are all stabilized at the same time.
- Maintains the stability of laser at any power level that is independently adjusted.

### The Idea: Closed loop feedback control



- 1. When laser rolls through a line its power goes through valley-peak-valley
- 2. Laser output power is sampled and turned into an electric signal
- 3. Signal is compared to the set value
- 4. Controller makes a decision whether to change the laser resonator
- 5. Command is sent to laser to compensate for the drift in laser resonator if necessary
- 6. Different from the traditional "dithering" approach: Piezo only moves to correct the residual drift of the well-stabilized resonator. There is no artificial frequency and power fluctuation introduced by the "dither."

### Line Tracker Sampling at 90-degrees



### Line Tracker Sampling at Small Angle



## LT Controller connections



## **Control Buttons and LEDs**



Push buttons (black):

•Mode SEL: Switch to open loop or close loop

•Profiling: scan for a profile of power pattern

•Scaling: Auto gain control

**•Up**: Open loop mode- manually increase driving voltage. Close loop mode-manually increase power.

•Down: Open loop mode-manually decrease driving voltage. Close loop mode- manually decrease power.

#### LED's

•Top red: Power indicator

•Closed Loop: Red-searching, Green-locked.

•Open Loop: Lights up in open loop mode

•Profiling: Blinks during profiling

•Signal LVL: fast blinks all the time. Green-power too low; Red- Power too high; Amber-Power OK

### Signal Outputs for Status Monitoring



Pin-1: HV monitor (analog, proportional to high voltage applied to piezo actuator) Pin-2: Signal-Too High (digital, same as signal lvl flashing red, signal too high) Pin-3: Mode (digital, low open loop, high close loop) Pin-4: Tracking (digital, in track when high) Pin-5: Ground Pin-6: Signal-Too Low (digital, same as signal lvl fashing green, signal too low) Pin-7: Laser Power (Analog, proportional to laser power) Pin-8: Profiling (digital, indicating profiling in process) Pin-9: reserved Note: All pins are output

### **Computer interface: Line Tracker Software**



NOTE: All functions of the LT controller are available here in the Line Tracker software. Some functions of the Line Tracker software are not available in the LT controller

## Computer interface /data logging



## Find the Right Working Point - Grating Tuned Lasers



Piezo moves around the <u>set point</u> to compensate the length of resonator. The recommended working point is at about 10% below the peak and more than 10% above the valley, to provide enough room for correction.

# **Close loop operation**

LineTracker-V23.vi After profiling this vellow File Edit Operate Tools Window Help setting line becomes a cross. Move the cross to CO<sub>2</sub> LineTracker approximately 10% below 1024 the desired peak on the Y Maximum 0 Y Minimum Access Laser Co. V2.4 power curve, select the [Voltage/Power Setting] [Laser Power] [Piezo Voltage] appropriate edge, then press 1024the "start tracking" button. 900 -The laser will start to be 800 tracked and stabilized. 700 Notice that the piezo voltage 600 (blue curve) moves up and 500 down to keep the laser 400 power (red curve) steady. 300 -200 -100 -0-180 200 240 20 40 60 80 100 140 220 260 120 160 Ó 280 Data Point AutoScaling Closed Path **Power Set** Start File Size 0 C:\Data AutoSave ON 840 Tracking 3600 ManualScale **File Name** Loop Mode Rising Stand By 127 CO2\_LOG\_ **SAVE to FILE** Time Scale Edge Tracking Serial Port 1 (S) 🔻 ScaleFactor Profiling Open Stop & Save ASRL2: Error 65 0

# **Operating Sequence**

- Wait for the laser to settle down thermally, typically 30 minutes or so.
- Open the Line Tracker program in computer.
- Activate the program by clicking arrow in upper left corner.
- Click AutoScaling button while at highest power point to optimize the gain.
- Click Close-loop button to start close-loop mode. Laser will go into profile mode first to provide a minimum-to-maximum voltage scan on piezo.
- After the scan evaluate the smoothness of curve. Select the smooth portion of the curve. Then select "rising edge" or "falling edge" depending accordingly.
- At this time click the Start Tracking button. The laser should go into closed loop operation.
- If at any time the laser comes out of closed loop run the above process again. The curve may have moved due to thermal fluctuation, or you may want to pick a different spot to lock the laser in.

## Upgrades to Software Version1.25-2010

- Compatible with Windows 7
- Same functionality as the older version
- May require Administrator privileges to write the initialization file into the root directory (commonly C)
- Sample of initialization file included in this CD.
- Effective Aug 2011